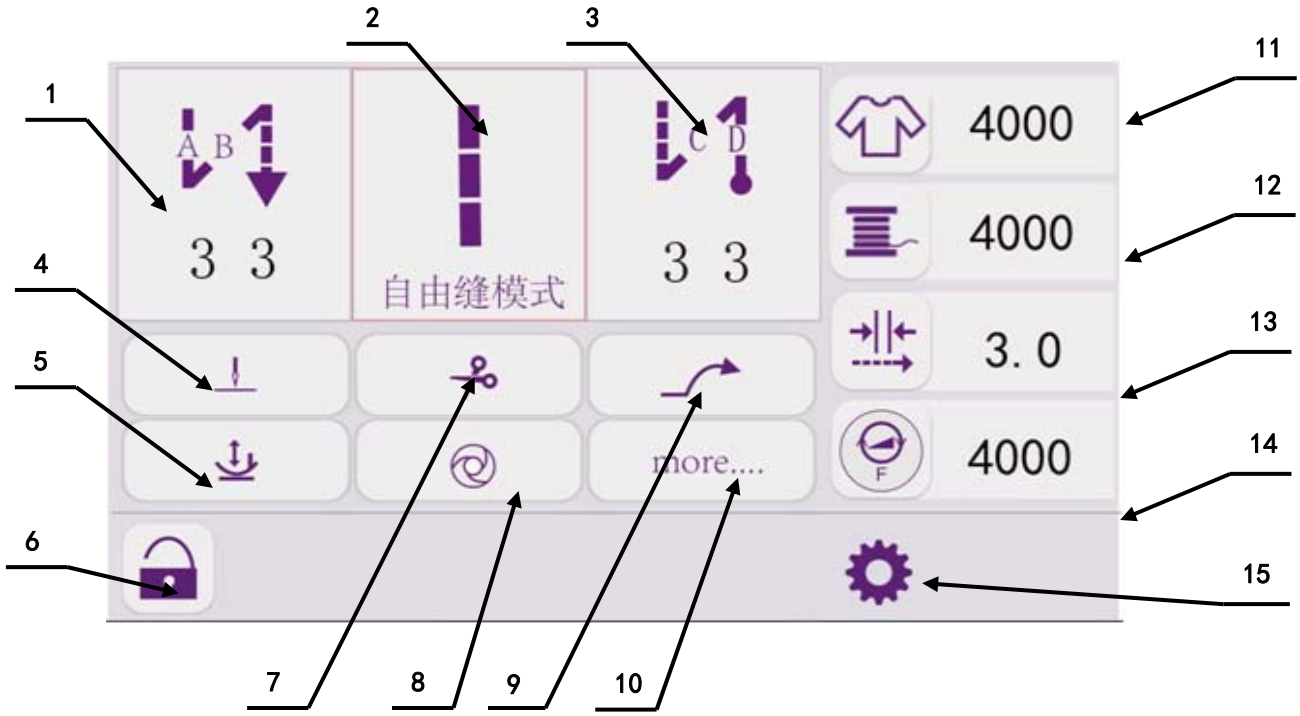
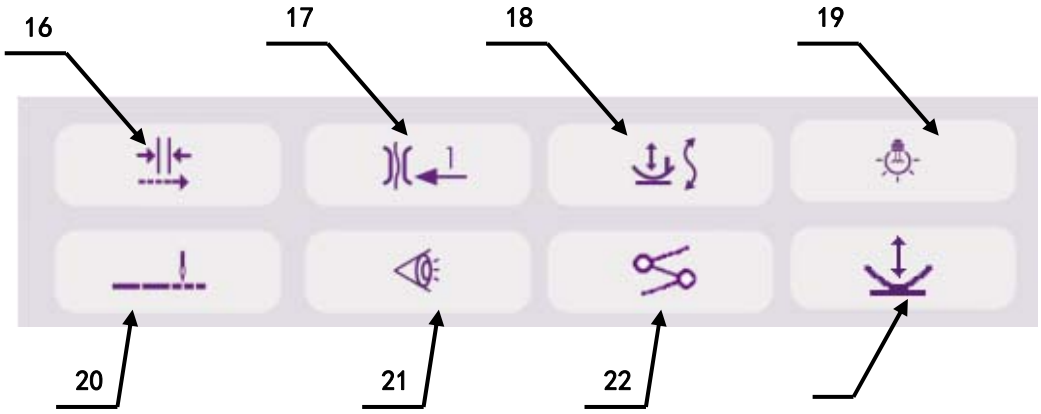
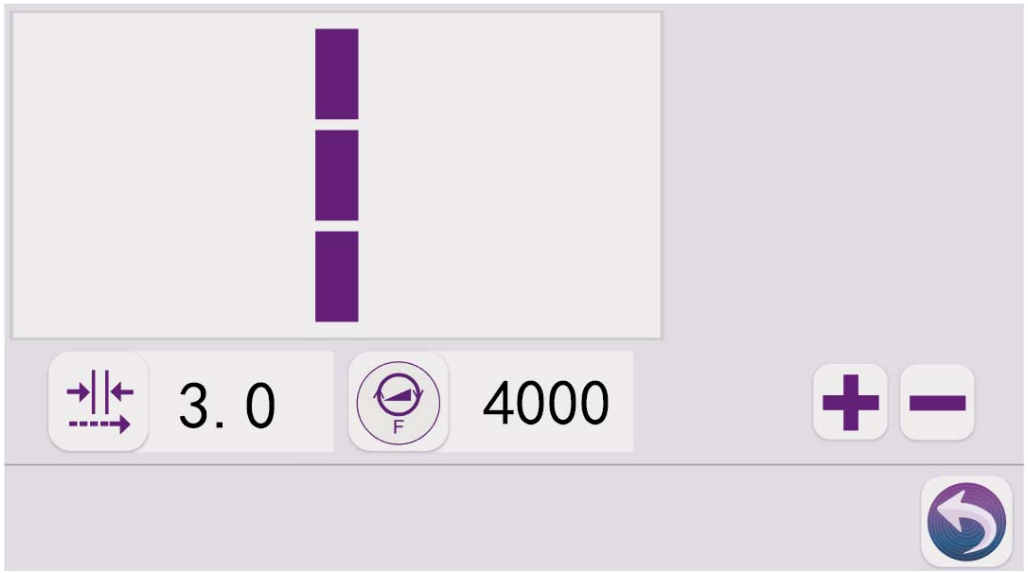
ENGLISH

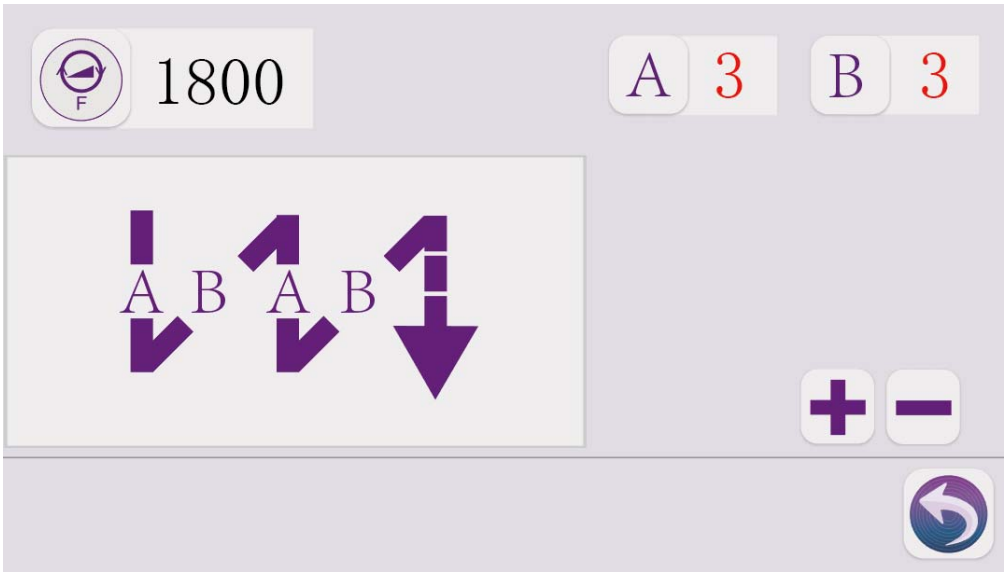
H9500N

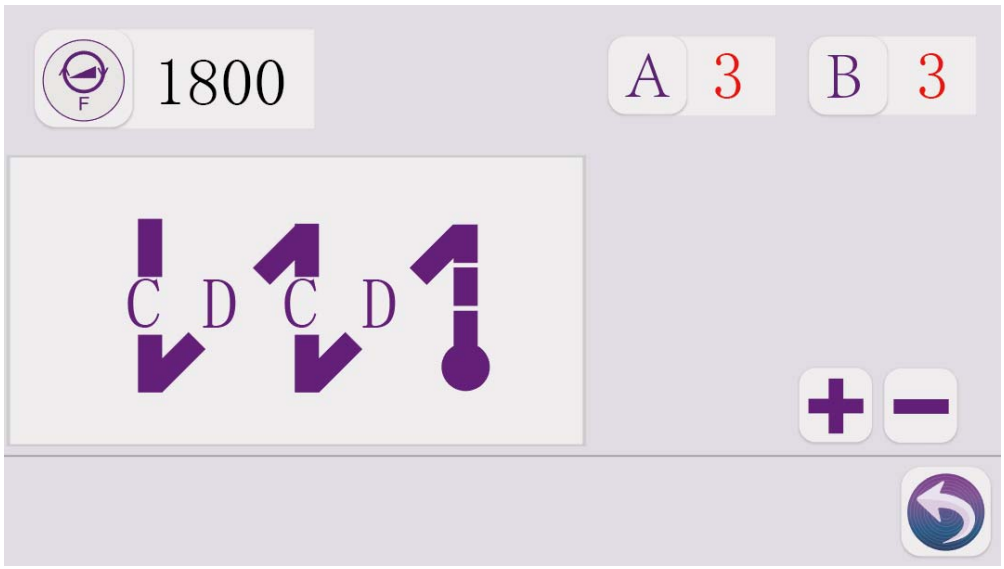
ELECTRICAL CONTROL BOX INSTRUCTION MANUAL

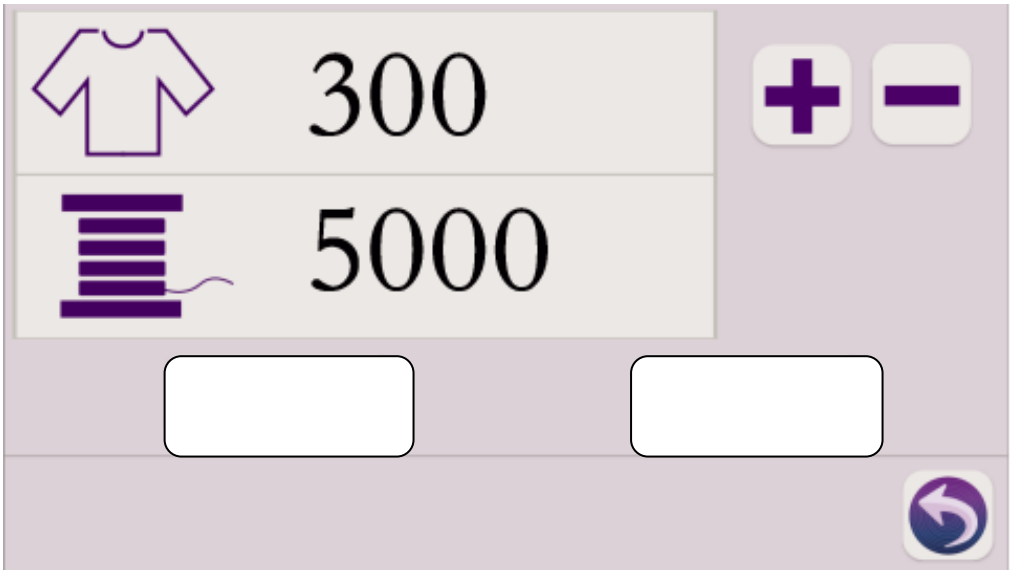

1
2
3
11
12
13
14
15
4
5
6
7
8
9
10
A B
3 3
自由缝模式
C D
3 3
4000
4000
3. 0
4000
more....

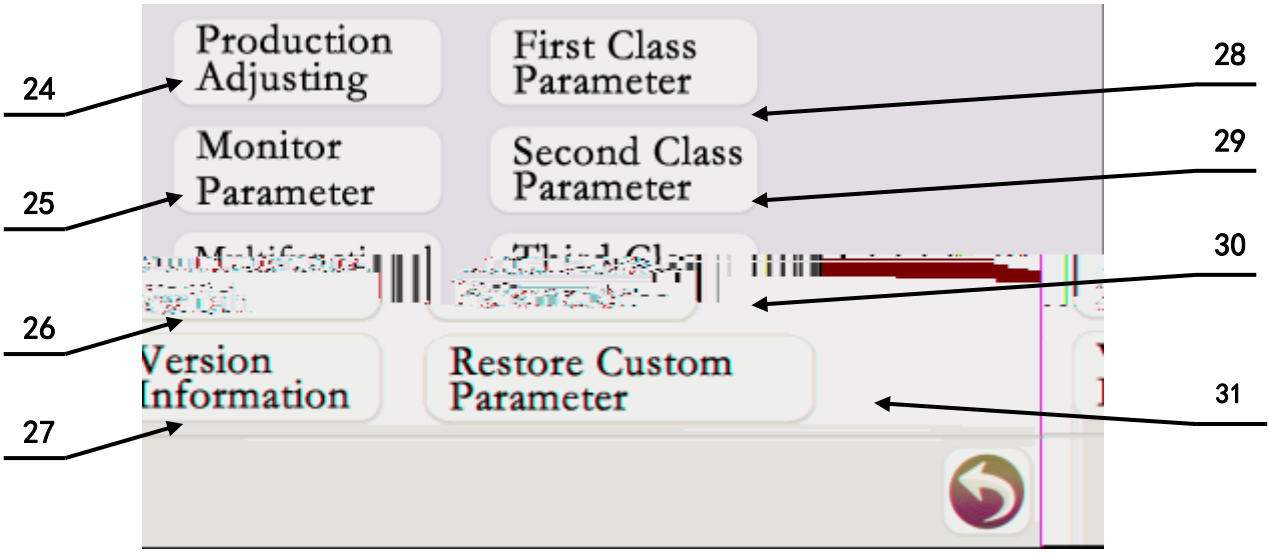

16
17
18
19
20
21
22

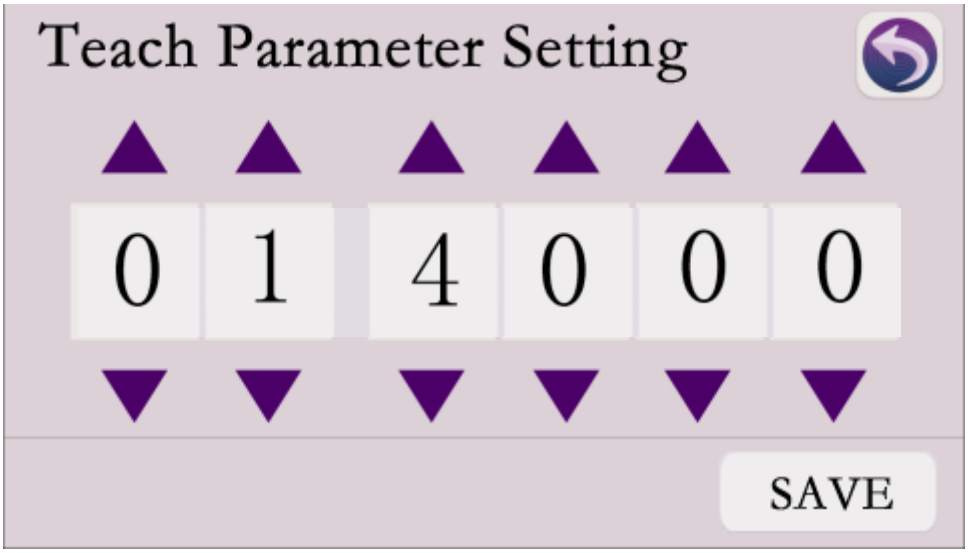

3. 0
4000

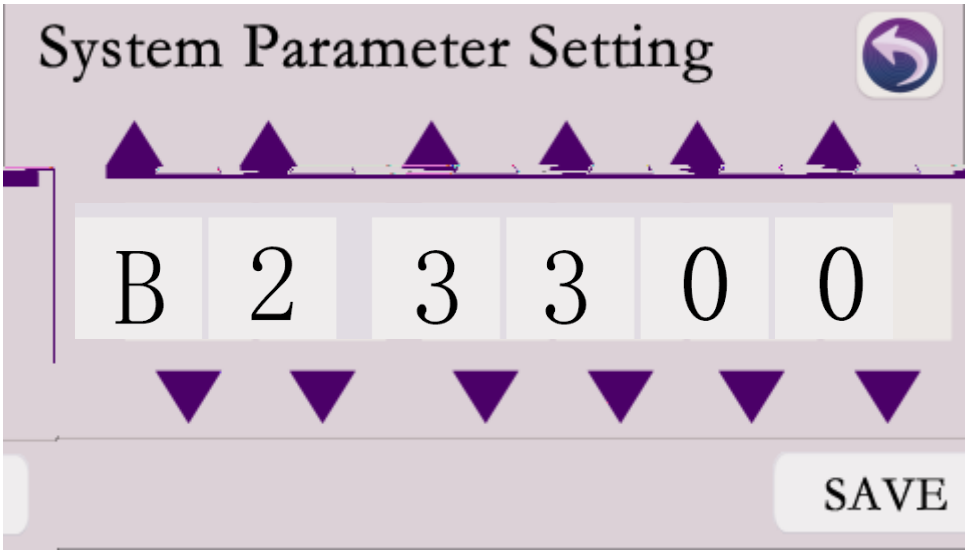

1800
A 3
B 3
A B A B


1800
A 3
B 3
C D C D

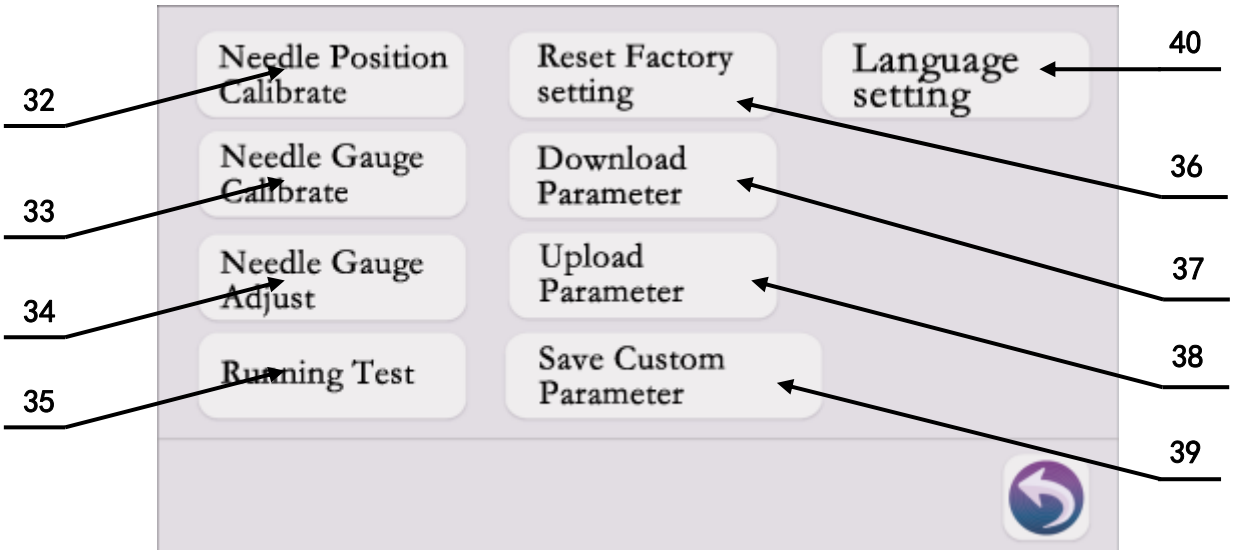

300
5000

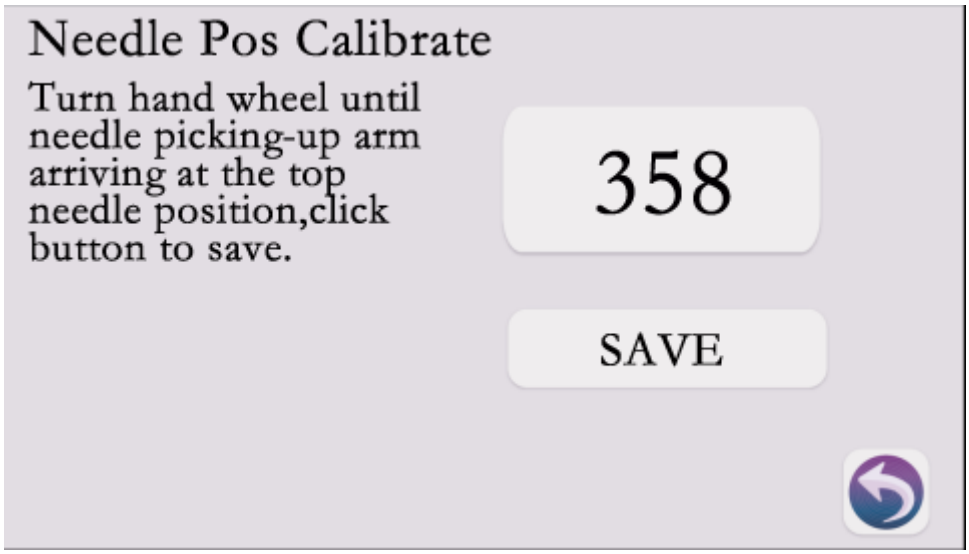

Production Adjusting
First Class Parameter
Monitor Parameter
Second Class Parameter
Version Information
Restore Custom Parameter
24
25
26
27
28
29
30
31

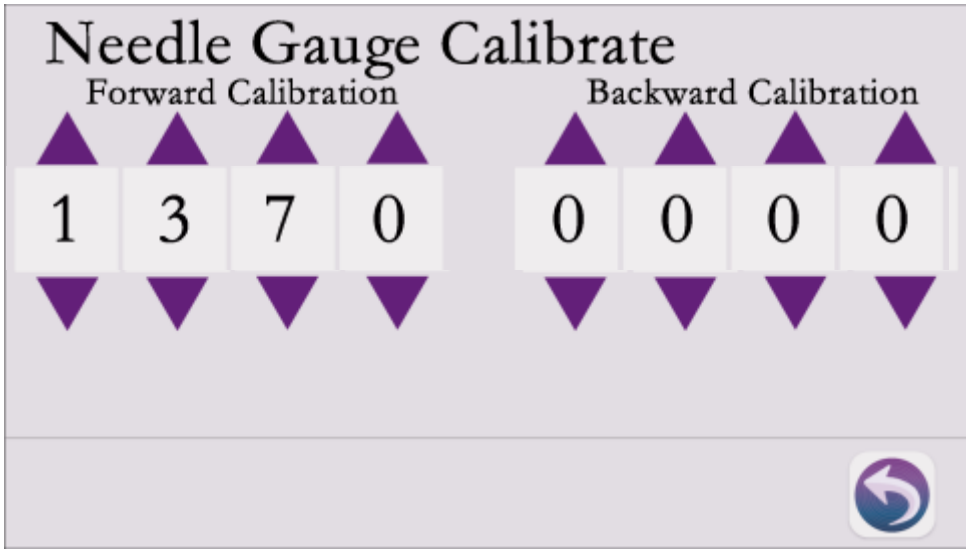

Teach Parameter Setting
0 1 4 0 0 0
SAVE

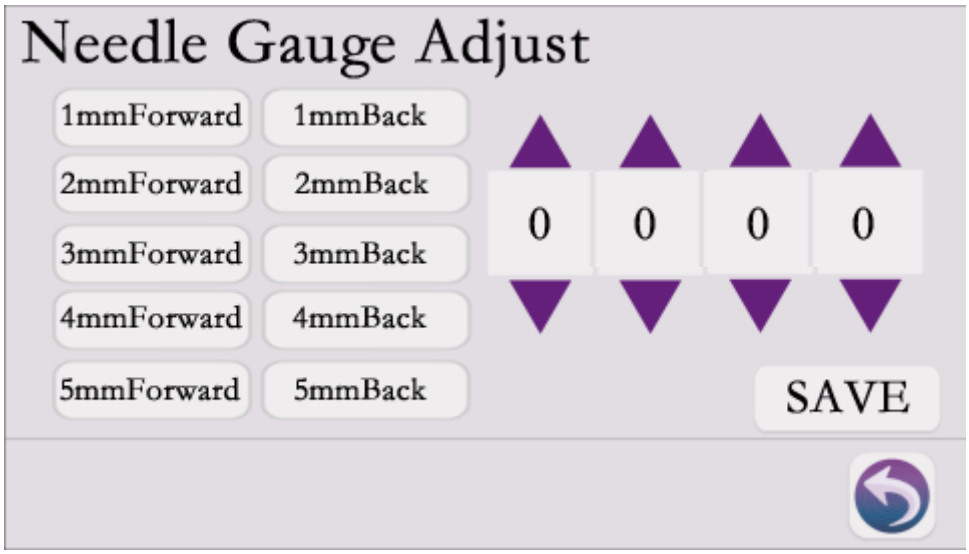

System Parameter Setting
B 2 3 3 0 0
SAVE

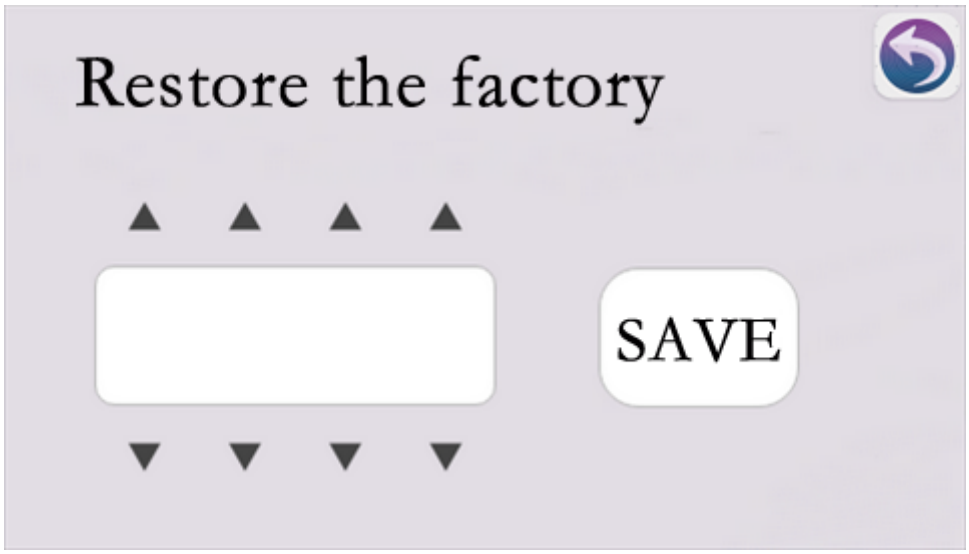

7
8
9
OK
4
5
6
1
2
3
Esc
0
.
DEL
Class
meter
nd Class
meter
Custom
er

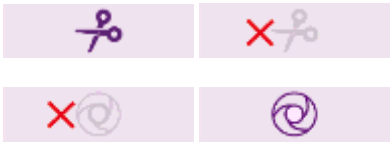

Needle Position Calibrate
Needle Gauge Calibrate
Needle Gauge Adjust
Running Test
Reset Factory setting
Download Parameter
Upload Parameter
Save Custom Parameter
Language setting
32
33
34
35
36
37
38
39
40


Needle Pos Calibrate
Turn hand wheel until needle picking-up arm arriving at the top needle position,click button to save.
358
SAVE

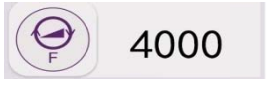

Needle Gauge Calibrate
Forward Calibration
Backward Calibration
1 3 7 0
0 0 0 0

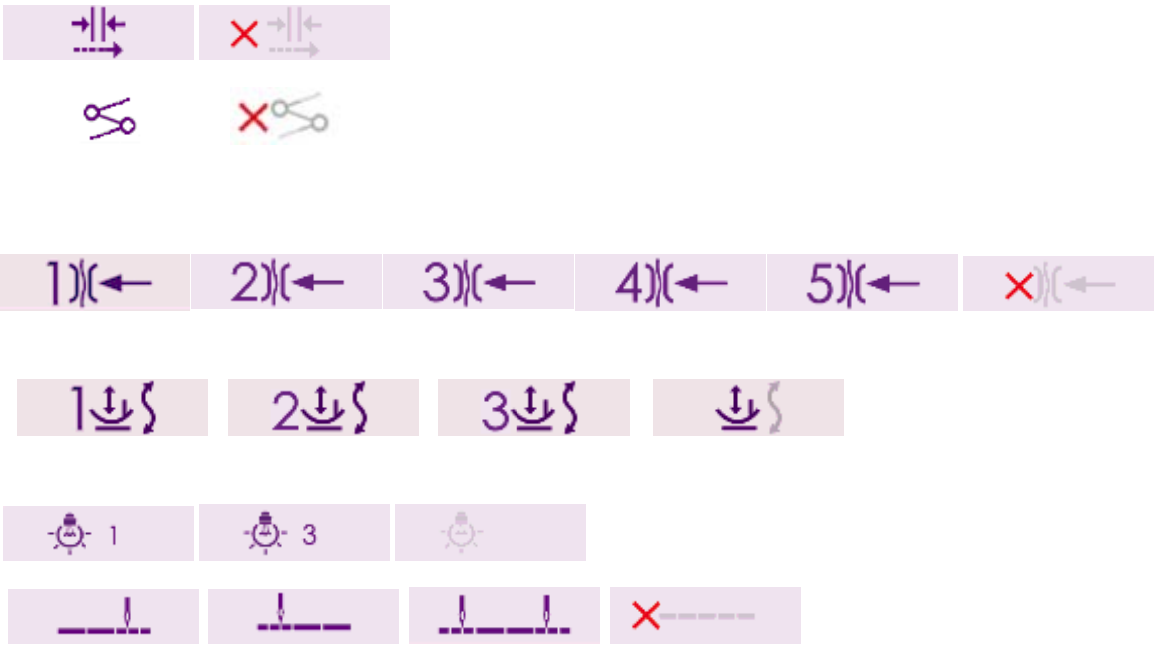

Needle Gauge Adjust
1mmForward
1mmBack
2mmForward
2mmBack
3mmForward
3mmBack
4mmForward
4mmBack
5mmForward
5mmBack
0 0 0 0
SAVE

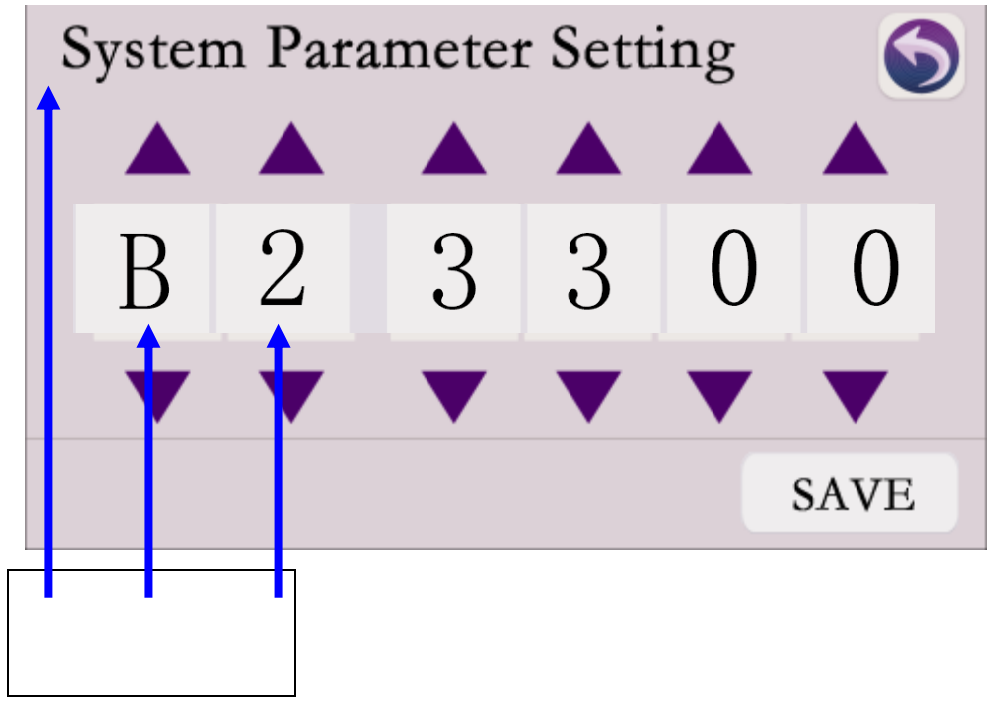

Restore the factory
SAVE

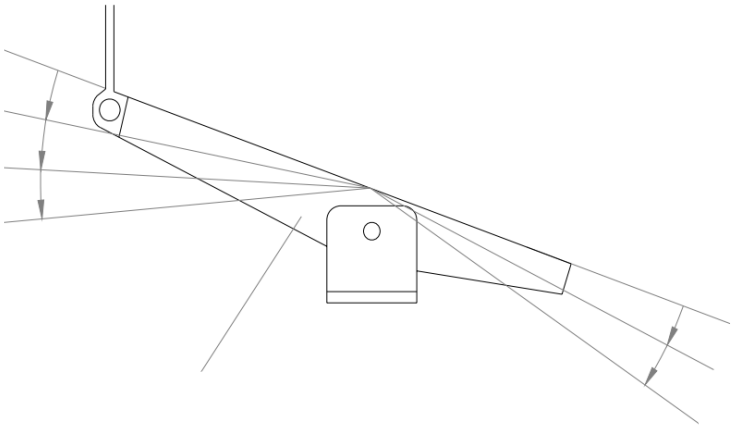


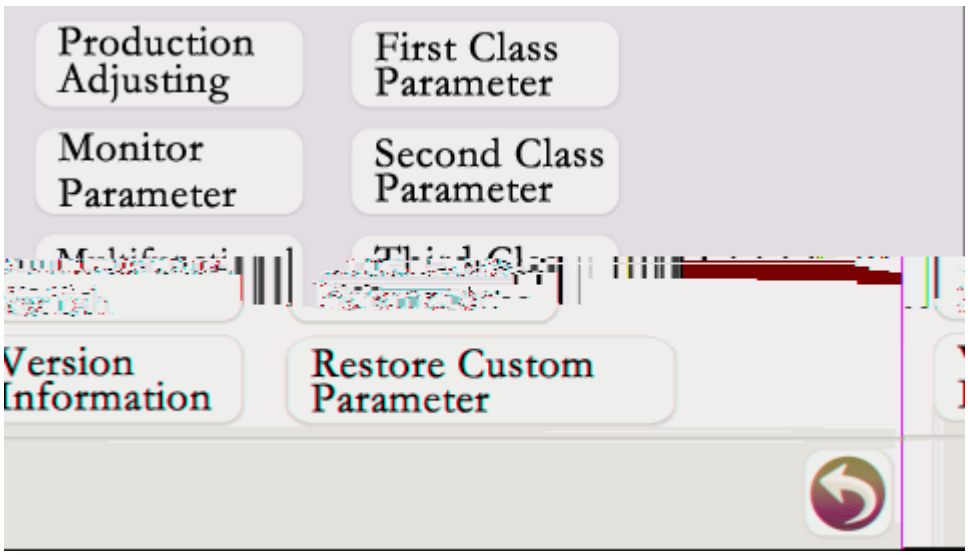
more....

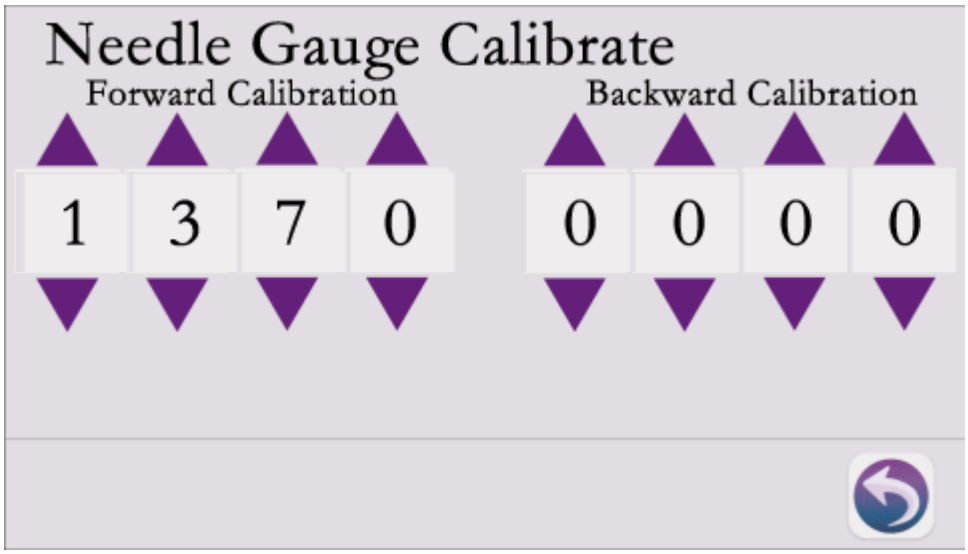


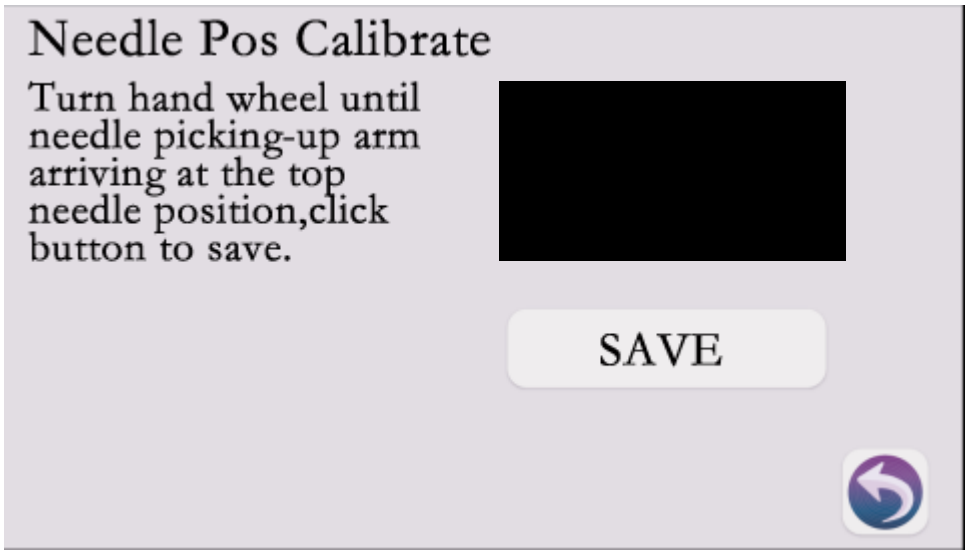

1
2
3
4
5
1
2
3
1
3

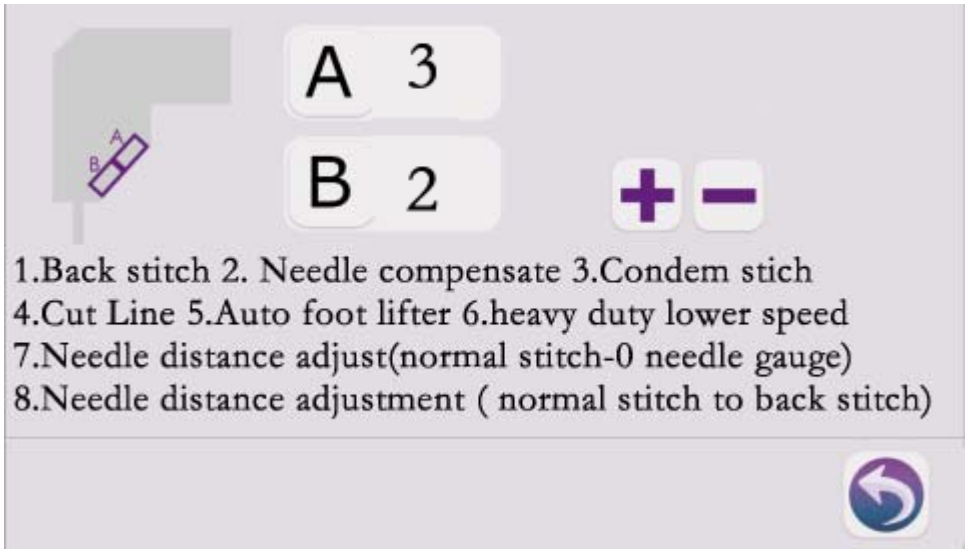

System Parameter Setting
B
2
3
3
0
0
SAVE

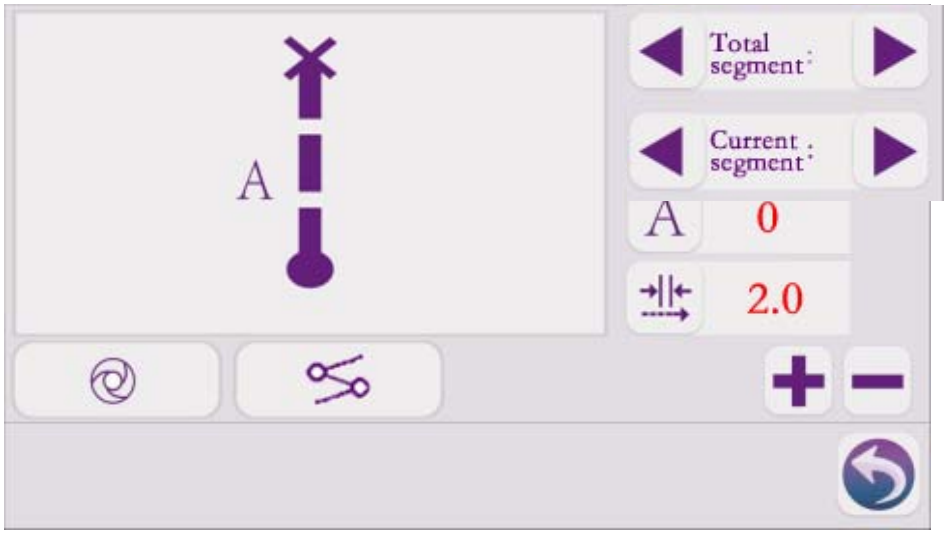


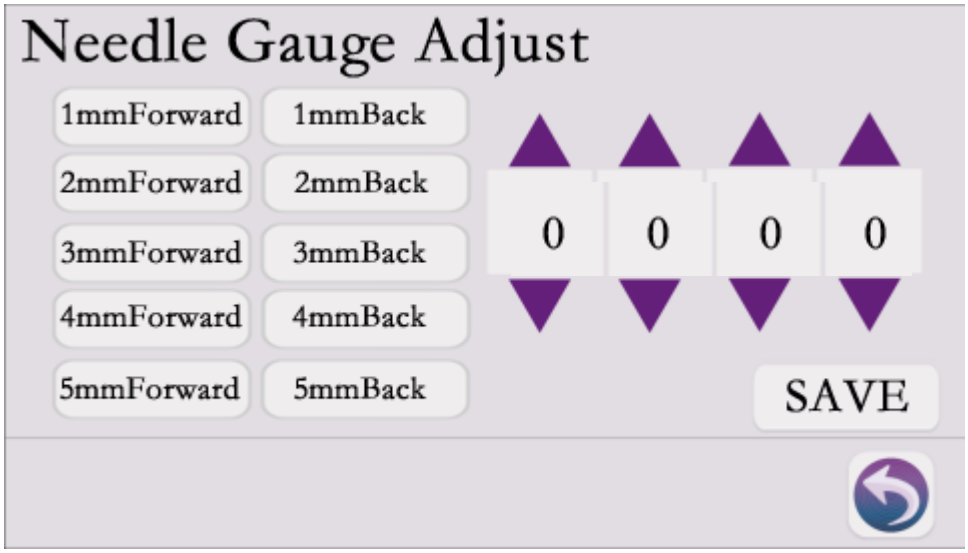

Production Adjusting
First Class Parameter
Monitor Parameter
Second Class Parameter
Version Information
Restore Custom Parameter

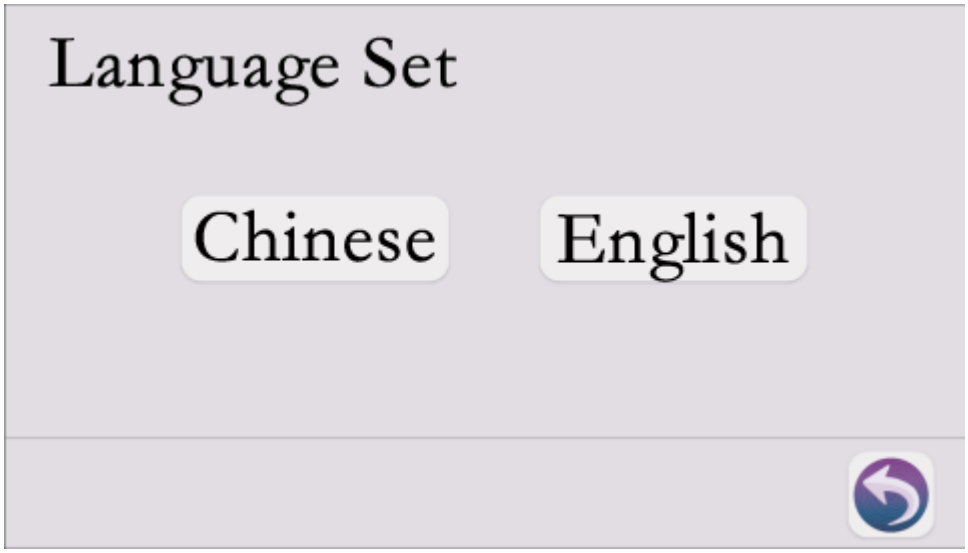

Needle Gauge Calibrate
Forward Calibration
Backward Calibration
1 3 7 0
0 0 0 0


Needle Pos Calibrate
Turn hand wheel until needle picking-up arm arriving at the top needle position,click button to save.
SAVE


A 3
B 2
1.Back stitch 2. Needle compensate 3.Condem stich
4.Cut Line 5.Auto foot lifter 6.heavy duty lower speed
7.Needle distance adjust(normal stitch-0 needle gauge)
8.Needle distance adjustment (normal stitch to back stitch)


A
Total segment
Current segment
A 0
2.0


Needle Gauge Adjust
1mmForward
1mmBack
2mmForward
2mmBack
3mmForward
3mmBack
4mmForward
4mmBack
5mmForward
5mmBack
0
0
0
0
SAVE


Language Set
Chinese
English

	Stitch count
	Trimming count
	Real machine speed
	Hall state
	Sector number
	Motor electrical angle
	Optical pulse count per revolution
	Busbar voltage
	Machine speed
	opposite current
	Initial angle
	Mechanical angle
	Sampling value of pedal voltage
	Actual gear ratio of head
	Motor accumulated running hours (Hour)
	High order part of DSP software version
	Low order part of DSP software version
	Analog input 2 sampling value (head analog button)
	Highest position: reverse sewing button; Second position: safety switch (Turnover) Third position: needle filling (The one in 2 Halls) Fourth position: over oil
	Highest position: low oil; Second position: broken line Third position: sensor Fourth position: head analog button

